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📍 United States of America

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🔧 SKILLS

- Python
- C++
- ROS & ROS2
- Linux
- C
- Matlab
- Simulink
- Machine Learning
- PyTorch
- TensorFlow
- Reinforcement Learning
- dSPACE SIL and HIL tools

🎓 INTERNSHIPS

Ford - Simulation Intern
(05/2018 - 08/2018)

dSPACE - Automated Driving Intern
(05/2017 - 08/2017)

TESLA - Test Automation Intern
(09/2016 - 12/2016)

Bosch - Electric Drives Intern
(05/2016 - 08/2016)

🗣️ LANGUAGES

English
Full Professional Proficiency

German
Full Professional Proficiency

Philipp Waeltermann

Senior Software Engineer and Developer

📁 WORK EXPERIENCE

● Senior Software Engineer (Level 8) Ford Motor Company

09/2021 - Present

Palo Alto, CA

Achievements/Tasks

- Guided software development of 10+ engineers by conducting code reviews and designing code architectures
- Initiated and guided projects with simulation, validation & verification, and fleet operations teams to provide support for L3 developers
- Planned the replacement of supplier-provided algorithms for sensor fusion, lidar perception, radar perception, and decision making with in-house solutions

● Software Engineer (Level 7) Ford Motor Company

02/2020 - 09/2021

Palo Alto, CA

Achievements/Tasks

- Developed ROS2 based framework for L3 prototype vehicle fleet
- Build processing pipeline for lane-level map used for path-planning algorithms
- Programmed CAN to ROS2 library for faster integration of new CAN-based devices using C++, C, Python, and Jinja2
- Integrated reinforcement learning based decision making algorithm
- Led cooperation with a computer vision startup for enhanced perception features
- Created guidelines for development and code review process of 5+ L3 developers

● Controls Engineer (Level 6) Ford Motor Company

02/2019 - 02/2020

Palo Alto, CA

Achievements/Tasks

- Designed and built L3 prototype vehicles using my knowledge of CAN, dSPACE MicroAutoBox and dSPACE ControlDesk
- Led integration of longitudinal controller using Simulink and object list processing using ROS & ROS2 for Python and C++
- Assisted with integration of lateral control and path-planning algorithms

🎓 EDUCATION

● Master of Science in Computer Science (Specialization: Machine Learning)

Georgia Institute of Technology

09/2020 - 12/2022

Online | GPA: 4.0

● Self-Driving Car Nanodegree Program Udacity

03/2019 - 09/2019

● Bachelor of Science in Mechanical Engineering (Minor: Computer Science) Michigan State University

08/2014 - 12/2018

East Lansing, MI | GPA: 4.0